

RAMPED – Summer 2016

Arduino Lesson Plan

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P = Pretest (think essential questions)

O = Objectives (measurable - see Bloom's taxonomy)

C = Catch (hook, anticipatory set, etc... use different senses, not a question)

A = Activity (procedure of what the students should do)

R = Review (how will students go over what they've learned?)

A = Assessment (formative and/or summative)

P = Posttest (same as pretest for comparison purposes)

S = Standards (Wyoming, NGSS, etc...) showcasing crosscutting concepts¹

Pretest Questions	What is an Arduino and how can it be used to control a robot?					
Objectives	Students will use an Arduino and program it and add the necessary hardware to operate a robot in their Pathways course to 100% success.					
Catch	The Beast					
Activity	<p>Provide teams of students with an Arduino uno starter kit and a box of sensors, and salvaged RC car and robot parts they can use to create a robot that can;</p> <ul style="list-style-type: none"> • automatically follow a line • automatically stop before it moves into a obstacle • can be controlled with a TV remote. <p>The engineering design process must be followed and all design details and sketches must be recorded in an engineering note book.</p>					
Review	<p>What was good about your design?</p> <p>What would you do differently?</p>					
Assessments	<p>TEAM Rubric; did the engineering note book match the project tha was designed 4 3 2 1</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td>Did the</td> <td>4 Yes</td> <td>3 Very</td> <td>2 Kinda</td> <td>1 Not so</td> </tr> </table>	Did the	4 Yes	3 Very	2 Kinda	1 Not so
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¹ <http://ngss.nsta.org/CrosscuttingConceptsFull.aspx>

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<p>See Career & Vocational Education PLDs – Performance Level Descriptors</p> <p>4 Advanced Performance 3 Proficient Performance 2 Basic Performance 1 Below Basic Performance</p>	design meet all the design criteria		nearly		much									
	Did the information in the Engineering notebook follow the design processes and match the project?	4 Yes	3 Very nearly	2 Kinda	1 Not so much									
	Did the robot complete the task	4 Yes	3 Very nearly	2 Kinda	1 Not so much									
	<p>Individual Rubric</p> <table border="1"> <tr> <td>CV12.2.1</td> <td>4 Met</td> <td>3 Nearly met</td> <td>2 Kinda Met</td> <td>1 Did not meet</td> </tr> <tr> <td>CV12.2.2</td> <td>4 Met</td> <td>3 Nearly met</td> <td>2 Kinda Met</td> <td>1 Did not</td> </tr> </table>					CV12.2.1	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet	CV12.2.2	4 Met	3 Nearly met	2 Kinda Met
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				meet
CV12.2.3	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
CV12.2.4	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
CV12.4.1	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
CV12.4.2	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
CV12.4.3	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
CV12.4.4	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
CV12.5.1	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
CV12.5.2	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
CV12.5.3	4 Met	3 Nearly	2 Kinda	1 Did

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			met	Met	not meet
	CV12.5.4	4 Met	3 Nearly met	2 Kinda Met	1 Did not meet
Posttest Questions (same as pretest questions)	What is an Arduino and how can it be used to control a robot?				
Standards Wyoming Career and Vocational Standards	WYCVE Standard 2 Communication and Collaboration CV12.2.1 CV12.2.2 CV12.2.3 CV12.2.4 WYCVE Standard 4 Technical Literacy CV12.4.1 CV12.4.2 CV12.4.3 CV12.4.4 WYCVE Standard 5 Technical Proficiency and Productivity CV12.5.1 CV12.5.2 CV12.5.3 CV12.5.4				
Crosscutting Concepts from NGSS	2 Cause and Effect 3 Scale, Proportion, and Quantity				